

HERON-LIKE STRATEGIES FOR NON-EUCLIDEAN TETRAHEDRAL VOLUME

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The note [3] presents the *Pseudo-Heron Formula* for the volume of a (Euclidean) tetrahedron in terms of the areas of its four faces and three *pseudo-faces*. It also introduces the *Heron Quartic* that encodes the volume of a “perfect” tetrahedron within a fourth-degree polynomial whose coefficients are expressed in terms of the areas of the four faces. This note offers a preliminary reconnaissance exercise in the quest for analogues of these results for tetrahedra in hyperbolic space.

Briefly, a hyperbolic tetrahedron’s volume is a function of the measures of its six dihedral angles. Basic “hedronometry” provides the necessary (and familiar) bridges between these angle measures and face-and-pseudo-face areas, guaranteeing a Pseudo-Heron result of some form. Likewise, “perfection” introduces dependencies between (proper) faces and pseudo-faces, allowing us to eliminate the latter from consideration and compute the volume of perfect tetrahedra in proper Heronic fashion: using their face areas alone.

At least, that’s the idea.

Unfortunately, the nature of the key hyperbolic volume function (it’s an integral) makes the consequent Pseudo-Heron result less than satisfying, as we cannot give a straightforward explicit (or implicit) formula; and, while perfection does admit elimination of pseudo-face elements, the relations involve 24th-degree polynomials. At best, our results are reduced to *strategies* on the order of “substitute appropriate solutions of some equations into the established hyperbolic volume formula”.

The final section of this note investigates the possibility of deriving a custom integral for at least the Pseudo-Heron case, though the author has not yet engaged in any significant investigation of that approach.

1. NOTATION

Denote the faces (and, without confusion, their areas) of a tetrahedron by W , X , Y , and Z ; let its pseudo-faces (and areas) be H , J , and K . Finally, name the dihedral angles (and their measures)

$$\begin{aligned} A &:= \angle YZ & B &:= \angle ZX & C &:= \angle XY \\ D &:= \angle WX & E &:= \angle WY & F &:= \angle WZ \end{aligned}$$

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To conserve space in long formulas, we employ the following "Morse Code" for cosines and sines of areas or angles:

$$\ddot{X} := \cos X \quad \bar{X} := \sin X$$

Moreover, for typographical convenience, as many formulas involving face areas feature trigonometric functions of *half*-areas, we write, eg, " X_2 " for " $\frac{X}{2}$ ". Thus, $\ddot{X}_2 := \cos \frac{X}{2}$.

2. TWO HEDRONOMETRIC FORMULAS

We pull two results from [4] for reference purposes.

The first result forms the bridge between dihedral angle information and face-and-pseudo-face area information (and it serves to formally define the pseudo elements). We introduce the convention that H , J , and K be bounded by 2π , although this consideration does not enter into discussion until Section 5, where it is invoked to settle a sign ambiguity.¹

Theorem 2.1 (The Second-and-a-Halfth ("2.5th") Law of Cosines).

$$\ddot{Y}_2\ddot{Z}_2 + \bar{Y}_2\bar{Z}_2\ddot{A} = \ddot{H}_2 = \ddot{W}_2\ddot{X}_2 + \bar{W}_2\bar{X}_2\ddot{D}$$

$$\ddot{Z}_2\ddot{X}_2 + \bar{Z}_2\bar{X}_2\ddot{B} = \ddot{J}_2 = \ddot{W}_2\ddot{Y}_2 + \bar{W}_2\bar{Y}_2\ddot{E}$$

$$\ddot{X}_2\ddot{Y}_2 + \bar{X}_2\bar{Y}_2\ddot{C} = \ddot{K}_2 = \ddot{W}_2\ddot{Z}_2 + \bar{W}_2\bar{Z}_2\ddot{F}$$

The second result is described as a "symmetric, face-agnostic" Law of Cosines, which here is dubbed the Third Law².

¹As described in [5], the pseudo-faces of a *Euclidean* tetrahedron are the projections of the figure into planes parallel to pairs of opposite edges. No geometric interpretation of non-Euclidean pseudo-faces is (yet) known; they merely serve to make the 2.5th Law of Cosines resemble the laws of cosines relating edges and angles of hyperbolic triangles. (As a point of history, Euclidean pseudo-faces first appeared as formal definitions in a Law of Cosines.) Observe that as, for instance, dihedral angle A ranges from 0 to π , the value of the expression for $\cos \frac{H}{2}$ ranges from $\cos \frac{Y-Z}{2}$ to $\cos \frac{Y+Z}{2}$. It is not unreasonable, then, to declare that H falls between $Y - Z$ and $Y + Z$; under this agreement, the fact that hyperbolic triangles have a maximum area of π provides an absolute maximum value of 2π on H .

²This is, in fact, an analogue of the Sum of Squares formula for Euclidean tetrahedra (from [3]): with each cosine term expanded as a power series, and then with all but the lowest-power—in this case, fourth-power—terms discarded, the Third Law reduces to

$$0 \approx \frac{1}{64} (W^2 + X^2 + Y^2 + Z^2 - H^2 - J^2 - K^2)^2$$

Thus, as a tetrahedron approaches infinitesimal size, the relation among its face areas approaches the Euclidean result, $W^2 + X^2 + Y^2 + Z^2 = H^2 + J^2 + K^2$.

Theorem 2.2 (The Third Law of Cosines).

$$\begin{aligned}
0 &= 1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 - 4\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2 \\
&\quad - \ddot{H}_2^2 - \ddot{J}_2^2 - \ddot{K}_2^2 - 2\ddot{H}_2\ddot{J}_2\ddot{K}_2 \\
&\quad + 2\ddot{H}_2 \left(\ddot{W}_2\ddot{X}_2 + \ddot{Y}_2\ddot{Z}_2 \right) + 2\ddot{J}_2 \left(\ddot{W}_2\ddot{Y}_2 + \ddot{Z}_2\ddot{X}_2 \right) + 2\ddot{K}_2 \left(\ddot{W}_2\ddot{Z}_2 + \ddot{X}_2\ddot{Y}_2 \right)
\end{aligned}$$

3. THE VOLUME FORMULA, AND THE PSEUDO-HERON STRATEGY

Derevniin and Mednykh [1] offer this formula for the volume of a (compact) tetrahedron with dihedral angles A, B, C, D, E, F :

$$(1) \quad V = -\frac{1}{4} \int_{\theta_0-\phi}^{\theta_0+\phi} \log \frac{\cos \frac{A+B+C+\theta}{2} \cos \frac{A+E+F+\theta}{2} \cos \frac{D+B+F+\theta}{2} \cos \frac{D+E+C+\theta}{2}}{\sin \frac{A+D+B+E+\theta}{2} \sin \frac{A+D+C+F+\theta}{2} \sin \frac{B+E+C+F+\theta}{2} \sin \frac{\theta}{2}} d\theta$$

where

$$\theta_0 := \tan^{-1} \frac{k_2}{k_1} \quad \phi := \tan^{-1} \frac{k_4}{k_3}$$

and

$$\begin{aligned}
k_1 &:= -(\cos(A+B+C+D+E+F) + \cos(A+D) + \cos(B+E) + \cos(C+F) \\
&\quad + \cos(D+E+F) + \cos(D+B+C) + \cos(A+E+C) + \cos(A+B+F))
\end{aligned}$$

$$\begin{aligned}
k_2 &:= \sin(A+B+C+D+E+F) + \sin(A+D) + \sin(B+E) + \sin(C+F) \\
&\quad + \sin(D+E+F) + \sin(D+B+C) + \sin(A+E+C) + \sin(A+B+F)
\end{aligned}$$

$$k_3 := 2(\sin A \sin D + \sin B \sin E + \sin C \sin F)$$

$$k_4 := \sqrt{k_1^2 + k_2^2 - k_3^2}$$

Importantly, the k_4 value is closely tied to the tetrahedron's Gram matrix, G :

$$k_4^2 = -4 \det \begin{pmatrix} 1 & -\cos A & -\cos B & -\cos F \\ -\cos A & 1 & -\cos C & -\cos E \\ -\cos B & -\cos C & 1 & -\cos D \\ -\cos F & -\cos E & -\cos D & 1 \end{pmatrix} = -4 \det G$$

Note that $\det G$ (and k_4) is non-zero for non-degenerate tetrahedra.³

³If $k_4 = 0$, then $\phi = 0$ or ϕ involves an indeterminate fraction requiring $k_3 = 0$. In the first case, the limits of integration in the volume formula match, yielding $V = 0$. In the second case, we must have at least three angles of measure 0.

Now, the Derevnin-Mednykh integral, coupled with the 2.5th Law of Cosines, amounts to a Pseudo-Heron Formula, as we have all angle references converted into expressions involving areas of faces and pseudo-faces.

Unfortunately, just "plugging in" doesn't yield attractive results. When expanded into trig functions of individual dihedral angles, the expressions for k_1 , k_2 , and k_3 involve not just cosines, but (un-squared) *sines*; at best, the 2.5th Law would have us express these using square roots, as in

$$\sin A = \frac{\sqrt{1 + 2\ddot{H}_2\ddot{Y}_2\ddot{Z}_2 - \ddot{H}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2}}{\ddot{Y}_2\ddot{Z}_2}$$

There seems to be little benefit, then, in converting the k s into face-and-pseudo-face form. Better to treat this as a *strategy*, instead of a formula:

Theorem 3.1 (The Pseudo-Heron Strategy). *To compute the volume of a hyperbolic tetrahedron from the areas of its faces and pseudo-faces, use the 2.5th Law of Cosines to determine the measures of the dihedral angles A , B , C , etc. (via their cosines), then substitute these measures into the Derevnin-Mednykh formula.*

We'll close this section with the observations that the "all cosines" nature of k_4 leads to a not-unpleasant face-and-pseudo-face form:⁴

$$k_4 = \frac{4}{\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2} \cdot \sqrt{\begin{pmatrix} \ddot{H}_2 + \ddot{J}_2\ddot{K}_2 - \ddot{W}_2\ddot{X}_2 - \ddot{Y}_2\ddot{Z}_2 \\ \ddot{J}_2 + \ddot{K}_2\ddot{H}_2 - \ddot{W}_2\ddot{Y}_2 - \ddot{Z}_2\ddot{X}_2 \\ \ddot{K}_2 + \ddot{H}_2\ddot{J}_2 - \ddot{W}_2\ddot{Z}_2 - \ddot{X}_2\ddot{Y}_2 \end{pmatrix}}$$

Perhaps the lesson of k_4 is that the whole of the "Pseudo-Heron Strategy" somehow admits reduction to a more compact form. Or perhaps not.

4. WHEN PERFECTION ISN'T PERFECT

A *perfect* tetrahedron⁵ is one in which each pair of opposite edges is orthogonal. The family of perfect tetrahedra includes right-corner tetrahedra (with three orthogonal edges meeting at a vertex) and regular tetrahedra (with equilateral faces). Perfection induces geometric dependencies that reduce the degrees of freedom in such a tetrahedron from six to four, so that face areas alone may characterize the figure. In Euclidean space, this leads to the *Heron Quartic* (see [3]), a polynomial that allows us to compute the figure's volume from its face areas; in hyperbolic space, perfection gets us as far as a 12th-degree polynomial with who-knows-how-many extraneous roots. Perfection *does* have an simplifying effect on the Gram matrix, however. We will review some salient properties of perfect tetrahedra here.

⁴This form does not arise simply from a straight substitution of the dihedral angle cosines with their face-and-pseudo-face equivalents. Doing *that* yields an unfactorable 96-term expression. The compact form comes from reducing the expansion *modulo* the Third Law of Cosines.

⁵Also known as an *orthogonal* tetrahedron.

Let α , β , and γ be the face-angles—in X , Y , and Z , respectively—having a common vertex, O . Let $a := OP$, $b := OQ$, and $c := OR$ be edges, with a opposite α , etc. We may assume that α is not a right angle. Therefore, the perpendicular from R meets OQ at a point $T \neq O$. Perfection requires that $RTP \perp OQ$, which implies that T is also the foot of the perpendicular from P to OQ . By the trigonometry of hyperbolic triangles,

$$\tanh |OT| = \tanh c \cos \alpha = \tanh a \cos \gamma$$

so that $\cos \alpha / \tanh a = \cos \gamma / \tanh c$. Symmetry provides that we have a value m such that⁶

$$(2) \quad \frac{\cos \alpha}{\tanh a} = \frac{\cos \beta}{\tanh b} = \frac{\cos \gamma}{\tanh c} = \frac{1}{m}$$

Writing \ddot{x} for $\cosh x$ and \bar{x} for $\sinh x$, we incorporate (2) into the hyperbolic Law of Cosines formula for $d := QR$.

$$\ddot{d} = \ddot{b}\ddot{c} - \bar{b}\bar{c}\ddot{\alpha} = \ddot{b}\ddot{c} - m\bar{b}\bar{c}\ddot{\beta} \cdot m\bar{c}\bar{\gamma} \cdot \ddot{\alpha} = \ddot{b}\ddot{c} \cdot (1 - m^2\ddot{\alpha}\ddot{\beta}\ddot{\gamma})$$

This leads to another symmetric result.⁷

$$(3) \quad \ddot{a}\ddot{d} = \ddot{b}\ddot{e} = \ddot{c}\ddot{f} = \ddot{a}\ddot{b}\ddot{c} \cdot (1 - m^2\ddot{\alpha}\ddot{\beta}\ddot{\gamma})$$

Indeed, hyperbolic and Euclidean hedronometry share a common characterization of perfection, namely:⁸

⁶The Euclidean analogue of this relation is

$$\frac{\cos \alpha}{a} = \frac{\cos \beta}{b} = \frac{\cos \gamma}{c} = \frac{1}{m}$$

⁷The Euclidean counterpart is

$$a^2 + d^2 = b^2 + e^2 = c^2 + f^2 = m^2 (\ddot{\alpha}^2 + \ddot{\beta}^2 + \ddot{\gamma}^2 - 2\ddot{\alpha}\ddot{\beta}\ddot{\gamma})$$

⁸The interconnectedness of results (3) and (4) is evident in, for instance, this relation involving the Gram matrix, G :

$$\ddot{a}\ddot{d} - \ddot{b}\ddot{e} = (\ddot{A}\ddot{D} - \ddot{B}\ddot{E}) \det G$$

For maximum symmetry, we can write

$$\frac{\ddot{a}\ddot{d} - \ddot{b}\ddot{e}}{\ddot{A}\ddot{D} - \ddot{B}\ddot{E}} = \frac{\ddot{b}\ddot{e} - \ddot{c}\ddot{f}}{\ddot{B}\ddot{E} - \ddot{C}\ddot{F}} = \frac{\ddot{c}\ddot{f} - \ddot{a}\ddot{d}}{\ddot{C}\ddot{F} - \ddot{A}\ddot{D}} = \det G$$

with the understanding that, if a non-degenerate tetrahedron's measurements zero-out the numerator of a component fraction, then (as $G \neq 0$) they must also zero the corresponding denominator. The analogue of this relation in Euclidean space is

$$\frac{(a^2 + d^2) - (b^2 + e^2)}{\ddot{A}\ddot{D} - \ddot{B}\ddot{E}} = \frac{(b^2 + e^2) - (c^2 + f^2)}{\ddot{B}\ddot{E} - \ddot{C}\ddot{F}} = \frac{(c^2 + f^2) - (a^2 + d^2)}{\ddot{C}\ddot{F} - \ddot{A}\ddot{D}} = \frac{-9V^2}{8WXYZ}$$

$$(4) \quad \cos A \cos D = \cos B \cos E = \cos C \cos F$$

From the 2.5th Law of Cosines, this ultimately implies that our hyperbolic faces and pseudo-faces are related thusly (introducing a "symmetric" parameter, M):

$$(5) \quad \ddot{H}_2^2 - \ddot{H}_2 (\ddot{W}_2 \ddot{X}_2 + \ddot{Y}_2 \ddot{Z}_2) = \ddot{J}_2^2 - \ddot{J}_2 (\ddot{W}_2 \ddot{Y}_2 + \ddot{Z}_2 \ddot{X}_2) = \ddot{K}_2^2 - \ddot{K}_2 (\ddot{W}_2 \ddot{Z}_2 + \ddot{X}_2 \ddot{Y}_2) =: M$$

In [3], the counterpart of this relation, along with the Sum of Squares identity, and the Pseudo-Heron formula for volume, gave rise to the Heron Quartic: we used the four equations to eliminate occurrences of three pseudo-face area quantities, leaving a polynomial involving only face areas and volume. As mentioned, the path to a similar result in hyperbolic space is unavailable.

Short of a volume formula, we can provide relations that express the dihedral angle measures A , B , C , etc, in terms of \ddot{W}_2 , \ddot{X}_2 , \ddot{Y}_2 , and \ddot{Z}_2 , but each relation is a product of two 12th-degree polynomials that defy simplification efforts. Given the length of these polynomials (on the order of thousands of terms), we won't display them here, but will provide a recipe for generating them with a computer algebra system such as Mathematica.

For maximum symmetry, we set a preliminary goal to be a polynomial expressing the value M from (5) in terms of proper-face areas. From there, converting to polynomials for the pseudo-face areas, and then for dihedral angles, will be straightforward.

Now, we gather together our relevant relations: equation (5), contributing three polynomials, and the Third Law of Cosines:

$$\begin{aligned} \text{polyH} &= H_2^2 - H_2 (W_2 X_2 + Y_2 Z_2) - M \\ \text{polyJ} &= J_2^2 - J_2 (W_2 Y_2 + Z_2 X_2) - M \\ \text{polyK} &= K_2^2 - K_2 (W_2 Z_2 + X_2 Y_2) - M \\ \text{loc3} &= 1 - W_2^2 - X_2^2 - Y_2^2 - Z_2^2 - 4 W_2 X_2 Y_2 Z_2 \\ &\quad - H_2^2 - J_2^2 - K_2^2 - 2 H_2 J_2 K_2 \\ &\quad + 2 H_2 (W_2 X_2 + Y_2 Z_2) + 2 J_2 (W_2 Y_2 + Z_2 X_2) \\ &\quad + 2 K_2 (W_2 Z_2 + X_2 Y_2) \end{aligned}$$

We can make our symbol-manipulator's task a bit less labor-intensive with a few definitions to reduce symbol clutter.

$$S_X := \ddot{W}_2 \ddot{X}_2 + \ddot{Y}_2 \ddot{Z}_2 \quad S_Y := \ddot{W}_2 \ddot{Y}_2 + \ddot{Z}_2 \ddot{X}_2 \quad S_Z := \ddot{W}_2 \ddot{Z}_2 + \ddot{X}_2 \ddot{Y}_2$$

$$S := 1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 - 4\ddot{W}_2 \ddot{X}_2 \ddot{Y}_2 \ddot{Z}_2$$

The transformed polynomials now feature the variables we wish to eliminate.

$$\begin{aligned} \text{polyH} &= H_2^2 - H_2 S_X - M \\ \text{polyJ} &= J_2^2 - J_2 S_Y - M \\ \text{polyK} &= K_2^2 - K_2 S_Z - M \\ \text{loc3} &= S - H_2^2 - J_2^2 - K_2^2 - 2 H_2 J_2 K_2 + 2 H_2 S_X + 2 J_2 S_Y + 2 K_2 S_Z \end{aligned}$$

Note that we can simplify the Third Law of Cosines even further:

$$\text{loc3} = S + H_2^2 + J_2^2 + K_2^2 - 2 H_2 J_2 K_2 - 6 M$$

At this point, we let our computer take over, repeatedly invoking, for instance, Mathematica's `Resultant` function to eliminate variables H2, J2, and K2 from the four polynomials. The result(ant?) is a 12th degree polynomial in M —with over a thousand terms involving S , S_x , S_y , and S_z —that starts out innocuously enough, and has a nicely-factorable constant term, but is a nightmare in the middle (here covered over with "..."):

$$\begin{aligned}
0 &= 256M^{12} - 2304M^{11} \\
&+ 32M^{10}(243 + 48S - 68S_X^2 - 68S_Y^2 - 68S_Z^2 - 36S_XS_YS_Z) \\
&+ \dots \\
&+ S(S + S_X^2)(S + S_Y^2)(S + S_Z^2) \\
&\quad (S + S_X^2 + S_Y^2)(S + S_Y^2 + S_Z^2)(S + S_Z^2 + S_X^2) \\
&\quad (S + S_X^2 + S_Y^2 + S_Z^2 - 2S_XS_YS_Z)
\end{aligned}$$

Expanding the S terms back into face-area terms doesn't improve things much. The number of terms in the polynomial grows to over *nineteen* thousand. However, the constant term breaks down into more factors:

$$\begin{aligned}
&\left(1 - \ddot{W}_2^2 - \ddot{X}_2^2\right) \left(1 - \ddot{W}_2^2 - \ddot{Y}_2^2\right) \left(1 - \ddot{W}_2^2 - \ddot{Z}_2^2\right) \\
&\left(1 - \ddot{X}_2^2 - \ddot{Y}_2^2\right) \left(1 - \ddot{Y}_2^2 - \ddot{Z}_2^2\right) \left(1 - \ddot{Z}_2^2 - \ddot{X}_2^2\right) \\
&\quad \left(1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 - 4\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2\right) \\
&\left(1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 + (\ddot{W}_2\ddot{X}_2 - \ddot{Y}_2\ddot{Z}_2)^2\right) \\
&\left(1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 + (\ddot{W}_2\ddot{Y}_2 - \ddot{Z}_2\ddot{X}_2)^2\right) \\
&\left(1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 + (\ddot{W}_2\ddot{Z}_2 - \ddot{X}_2\ddot{Y}_2)^2\right) \\
&\left(\begin{aligned} &1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 - 4\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2 \\ &(\ddot{W}_2\ddot{X}_2 - \ddot{Y}_2\ddot{Z}_2)^2 + (\ddot{W}_2\ddot{Y}_2 - \ddot{Z}_2\ddot{X}_2)^2 + (\ddot{W}_2\ddot{Z}_2 - \ddot{X}_2\ddot{Y}_2)^2 \\ &- 2(\ddot{W}_2\ddot{X}_2 - \ddot{Y}_2\ddot{Z}_2)(\ddot{W}_2\ddot{Y}_2 - \ddot{Z}_2\ddot{X}_2)(\ddot{W}_2\ddot{Z}_2 - \ddot{X}_2\ddot{Y}_2) \end{aligned} \right)
\end{aligned}$$

Note the first few factors admit further trigonometric simplification. For instance,

$$1 - \ddot{W}_2^2 - \ddot{X}_2^2 = -\frac{1}{2}(\cos W + \cos X) = -\cos\left(\frac{W+X}{2}\right)\cos\left(\frac{W-X}{2}\right)$$

So far, any further sense in the M polynomial has been elusive.

Nevertheless, converting the M polynomial into, say, an \ddot{H}_2 polynomial is as simple as a substitution: replace M with $\ddot{H}_2^2 - \ddot{H}_2S_X$. The resulting polynomial has degree 24, but factors into polynomials of degree 12 (with, respectively, 131 and 229 terms).

$$\begin{aligned}
&\left(16\ddot{H}_2^{12} - 64\ddot{H}_2^{11}S_X + \dots + S(S + S_Y^2)(S + S_Z^2)(S + S_Y^2 + S_Z^2)\right) \\
&\left(\begin{aligned} &16\ddot{H}_2^{12} - 128\ddot{H}_2^{11}S_X + \dots \\ &+(S + S_X^2)(S + S_X^2 + S_Y^2)(S + S_X^2 + S_Z^2)(S + S_X^2 + S_Y^2 + S_Z^2 - 2S_XS_YS_Z) \end{aligned} \right)
\end{aligned}$$

These polynomials, though shorter than the M polynomial, aren't any less daunting to study.

But, of course, if we seek to tie back into the formula for tetrahedral volume, then we shouldn't stop at the pseudo-face level; we should proceed to the dihedral angle level. The 2.5th Law of Cosines provides the necessary bridges—for instance, $\ddot{H}_2 = \ddot{Y}_2\ddot{Z}_2 + \bar{Y}_2\bar{Z}_2\ddot{A}$ —for converting our polynomial. Writing A_{XY} for $\bar{Y}_2\bar{Z}_2\ddot{A}$, we have⁹

$$\begin{pmatrix} 16A_{YZ}^{12} - 64A_{YZ}^{11} \left(\ddot{W}_2\ddot{X}_2 - 2\ddot{Y}_2\ddot{Z}_2 \right) \\ + \cdots \\ + \bar{Y}_2^2\bar{Z}_2^2 \left(1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Y}_2^2 + 2\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2 \right) \\ \left(1 - \ddot{W}_2^2 - \ddot{X}_2^2 - \ddot{Z}_2^2 + 2\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2 \right) \\ \left(\bar{W}_2^2\bar{Y}_2^2\bar{Z}_2^2 - (\ddot{X}_2 - \ddot{W}_2\ddot{Y}_2\ddot{Z}_2)^2 \right) \\ \left(\bar{X}_2^2\bar{Y}_2^2\bar{Z}_2^2 - (\ddot{W}_2 - \ddot{X}_2\ddot{Y}_2\ddot{Z}_2)^2 \right) \end{pmatrix} \\ \\ \begin{pmatrix} 16A_{YZ}^{12} + 64A_{YZ}^{11} \left(\ddot{Y}_2\ddot{Z}_2 - 2\ddot{W}_2\ddot{X}_2 \right) \\ + \cdots \\ + \bar{W}_2^2\bar{X}_2^2 \left(1 - \ddot{W}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 - 2\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2 \right) \\ \left(1 - \ddot{X}_2^2 - \ddot{Y}_2^2 - \ddot{Z}_2^2 + 2\ddot{W}_2\ddot{X}_2\ddot{Y}_2\ddot{Z}_2 \right) \\ \left(\bar{W}_2^2\bar{X}_2^2\bar{Y}_2^2 - (\ddot{Z}_2 - \ddot{W}_2\ddot{X}_2\ddot{Y}_2)^2 \right) \\ \left(\bar{W}_2^2\bar{X}_2^2\bar{Z}_2^2 - (\ddot{Y}_2 - \ddot{W}_2\ddot{X}_2\ddot{Z}_2)^2 \right) \end{pmatrix}$$

Likewise for the other dihedral quantities, $B_{ZX} := \bar{Z}_2\bar{X}_2\ddot{B}$, $C_{XY} := \bar{X}_2\bar{Y}_2\ddot{C}$, $D_{WX} := \bar{W}_2\bar{X}_2\ddot{D}$, $E_{WY} := \bar{W}_2\bar{Y}_2\ddot{E}$, and $F_{WZ} := \bar{W}_2\bar{Z}_2\ddot{F}$. Currently, we have no information on how many roots of these polynomials may be extraneous, either inherently as individuals (being non-real values or having greater-than-one absolute values), or for failing collectively to satisfy relations such as (4). One should hope for a clear method of weeding out extraneous roots from “appropriate” ones, for otherwise, the face areas of a perfect tetrahedron provide as many as 24 “candidate” measures for each dihedral angle, determining $24^6 = 191,102,976$ different tetrahedra (or $24^6/24 = 7,962,624$, when accounting for tetrahedral symmetries). Nevertheless, we have a foundation for a strategy for computing the volume of our tetrahedron.

Theorem 4.1 (The Perfect Heron Strategy). *To compute the volume of a perfect hyperbolic tetrahedron from the areas of its faces, use the family of polynomials in A_{YZ} , etc, to determine the candidates for the measures of the dihedral angles A , B , C , etc. Then substitute the “appropriate” measures into the Derevniin-Mednykh formula.*

Not the most satisfying of results.

⁹Despite appearances in the abbreviated display, the factors *do not* simply exchange Y and Z for W and X . The first factor, when expanded, has 672 terms; the second, 923.

On a more optimistic note: Perfection provides *definite* simplification of a tetrahedron’s “hedronometric” Gram matrix representation (although pseudo-face elements remain). Multiplying each factor by one of \ddot{H}_2 , \ddot{J}_2 , and \ddot{K}_2 —and dividing out to compensate—leaves three equivalent factors.

$$\begin{aligned}
\det G &:= \frac{-4}{\bar{W}_2^2 \bar{X}_2^2 \bar{Y}_2^2 \bar{Z}_2^2} \cdot \begin{pmatrix} \ddot{J}_2 \ddot{K}_2 + \ddot{H}_2 - \ddot{W}_2 \ddot{X}_2 - \ddot{Y}_2 \ddot{Z}_2 \\ \ddot{H}_2 \ddot{K}_2 + \ddot{J}_2 - \ddot{W}_2 \ddot{Y}_2 - \ddot{Z}_2 \ddot{X}_2 \\ \ddot{H}_2 \ddot{J}_2 + \ddot{K}_2 - \ddot{W}_2 \ddot{Z}_2 - \ddot{X}_2 \ddot{Y}_2 \end{pmatrix} \\
&= \frac{-4}{\bar{W}_2^2 \bar{X}_2^2 \bar{Y}_2^2 \bar{Z}_2^2} \cdot \frac{1}{\ddot{H}_2 \ddot{J}_2 \ddot{K}_2} \cdot \begin{pmatrix} \ddot{H}_2 \ddot{J}_2 \ddot{K}_2 + \ddot{H}_2^2 - \ddot{H}_2 (\ddot{W}_2 \ddot{X}_2 + \ddot{Y}_2 \ddot{Z}_2) \\ \ddot{H}_2 \ddot{J}_2 \ddot{K}_2 + \ddot{J}_2^2 - \ddot{J}_2 (\ddot{W}_2 \ddot{Y}_2 + \ddot{Z}_2 \ddot{X}_2) \\ \ddot{H}_2 \ddot{J}_2 \ddot{K}_2 + \ddot{K}_2^2 - \ddot{K}_2 (\ddot{W}_2 \ddot{Z}_2 + \ddot{X}_2 \ddot{Y}_2) \end{pmatrix} \\
&= \frac{-4 \left(\ddot{H}_2 \ddot{J}_2 \ddot{K}_2 + M \right)^3}{\bar{W}_2^2 \bar{X}_2^2 \bar{Y}_2^2 \bar{Z}_2^2 \ddot{H}_2 \ddot{J}_2 \ddot{K}_2}
\end{aligned}$$

One might wish to take a further step of expressing the perfected $\det G$ in terms of face areas alone; or in terms of pseudo-face areas and M (as these values dominate the above formula). Either way may show $\det G$ to be a more suitable “symmetric” parameter than M (which was defined rather arbitrarily). This author, unfortunately, has yet to find either the patience required for his aging computer to crank through the brute-force manipulations ... or the insight required to side-step them.

5. SYMMETRIC TETRAHEDRA: USING A CUSTOM-TAILORED VOLUME INTEGRAL

The article [2] side-steps the Derevnin-Mednykh integral (1), deriving from differential principals an integral tailored to the special case of *symmetric* hyperbolic tetrahedra, which are defined by having congruent opposing dihedral angles (say, A , B , and C); such tetrahedra have congruent faces with area W satisfying

$$(6) \quad \bar{W} = \frac{\ddot{A} + \ddot{B} + \ddot{C} - 1}{(1 - \ddot{A})(1 - \ddot{B})(1 - \ddot{C})} \sqrt{1 - 2\ddot{A}\ddot{B}\ddot{C} - \ddot{A}^2 - \ddot{B}^2 - \ddot{C}^2}$$

The new integral is parameterized by three angles (A , B , C) meeting at a vertex (or, equivalently, surrounding a face).

$$(7) \quad V = \int_{v_0}^{\infty} \arcsin \frac{\ddot{A}}{\sqrt{v^2 + 1}} + \arcsin \frac{\ddot{B}}{\sqrt{v^2 + 1}} + \arcsin \frac{\ddot{C}}{\sqrt{v^2 + 1}} - \arcsin \frac{1}{\sqrt{v^2 + 1}} \frac{dv}{v}$$

where

$$(8) \quad v_0 = \frac{1 - 2\ddot{A}\ddot{B}\ddot{C} - \ddot{A}^2 - \ddot{B}^2 - \ddot{C}^2}{\sqrt{(1 - \ddot{A} + \ddot{B} + \ddot{C})(1 + \ddot{A} - \ddot{B} + \ddot{C})(1 + \ddot{A} + \ddot{B} - \ddot{C})(-1 + \ddot{A} + \ddot{B} + \ddot{C})}}$$

This result, being expressed entirely in cosines of the figure's dihedral angles, has a decidedly more hedronometry-friendly flavor than the Derevnin-Mednykh formula. We can easily use the 2.5th Law of Cosines to re-write the equation in terms of common face area (W) and pseudo-face areas (H, J, K) by making these substitutions:

$$(9) \quad \ddot{A} = \frac{\ddot{H}_2 - \ddot{W}_2^2}{\ddot{W}_2^2} \quad \ddot{B} = \frac{\ddot{J}_2 - \ddot{W}_2^2}{\ddot{W}_2^2} \quad \ddot{C} = \frac{\ddot{K}_2 - \ddot{W}_2^2}{\ddot{W}_2^2}$$

However, this analysis gets more notationally compact if we work in terms of *half*-angles (A_2, B_2, C_2) and *quarter*-pseudo-faces (H_4, J_4, K_4) while shifting our trigonometric affections away from cosine and toward sine. We start by noting that (8) implies¹⁰

$$(10) \quad \bar{A}_2 = \sqrt{\frac{1 - \ddot{A}}{2}} = \sqrt{\frac{1 - \ddot{H}_2}{2\ddot{W}_2^2}} = \sqrt{\frac{\bar{H}_4^2}{\bar{W}_2^2}} = \frac{\bar{H}_4}{\bar{W}_2} \quad \bar{B}_2 = \frac{\bar{J}_4}{\bar{W}_2} \quad \bar{C}_2 = \frac{\bar{K}_4}{\bar{W}_2}$$

The Third Law of Cosines provides a convenient factorization

$$0 = \left((\bar{W}_2^2 - \bar{H}_4^2 - \bar{J}_4^2 - \bar{K}_4^2) + 2\bar{H}_4\bar{J}_4\bar{K}_4 \right) \left((\bar{W}_2^2 - \bar{H}_4^2 - \bar{J}_4^2 - \bar{K}_4^2) - 2\bar{H}_4\bar{J}_4\bar{K}_4 \right)$$

that implies

$$\bar{W}_2^2 - \bar{H}_4^2 - \bar{J}_4^2 - \bar{K}_4^2 = \pm 2\bar{H}_4\bar{J}_4\bar{K}_4$$

We deduce that the “ \pm ” should be “ $+$ ”: the product $2\bar{H}_4\bar{J}_4\bar{K}_4$ is (assumed) non-negative; the left-hand side is equivalent to $\frac{1}{2}\bar{W}_2^2 (\ddot{A} + \ddot{B} + \ddot{C} - 1)$, which is also non-negative.¹¹ Thus,

$$\bar{W}_2^2 = 2\bar{H}_4\bar{J}_4\bar{K}_4 + \bar{H}_4^2 + \bar{J}_4^2 + \bar{K}_4^2$$

so that the integration endpoint v_0 from (7) becomes

$$v_0 = \frac{\bar{H}_4\bar{J}_4\bar{K}_4 \left(1 - 2\bar{H}_4\bar{J}_4\bar{K}_4 - \bar{H}_4^2 - \bar{J}_4^2 - \bar{K}_4^2 \right)}{\left(2\bar{H}_4\bar{J}_4\bar{K}_4 + \bar{H}_4^2 + \bar{J}_4^2 + \bar{K}_4^2 \right) \sqrt{(\bar{H}_4 + \bar{J}_4\bar{K}_4)(\bar{J}_4 + \bar{H}_4\bar{K}_4)(\bar{H}_4\bar{J}_4 + \bar{K}_4)}}$$

¹⁰Knowing that $\sin \frac{A}{2}$, $\sin \frac{B}{2}$, $\sin \frac{C}{2}$, and $\sin \frac{W}{2}$ are non-negative —because A, B, C , and W are bounded above by π — and taking $\sin \frac{H}{4}$, $\sin \frac{J}{4}$, and $\sin \frac{K}{4}$ also non-negative on the assumption that H, J , and K are bounded above by 2π .

¹¹The expression $\ddot{A} + \ddot{B} + \ddot{C} - 1$ appears in (6) as a factor, among other non-negative factors, of a non-negative quantity.

We can simplify the integral itself ever-so-slightly via the change of variables $t := v\bar{W}_2^2$. With this, we have

Theorem 5.1 (The Pseudo-Heron Formula for Volume of a Symmetric Hyperbolic Tetrahedron). *A symmetric hyperbolic tetrahedron with pseudo-face areas H , J , and K (and face area W) has volume given by*

$$(11) \quad V = \int_{t_0}^{\infty} \arcsin \frac{\bar{W}_2^2 - 2\bar{H}_4^2}{\sqrt{t^2 + \bar{W}_2^4}} + \arcsin \frac{\bar{W}_2^2 - 2\bar{J}_4^2}{\sqrt{t^2 + \bar{W}_2^4}} + \arcsin \frac{\bar{W}_2^2 - 2\bar{K}_4^2}{\sqrt{t^2 + \bar{W}_2^4}} - \arcsin \frac{\bar{W}_2^2}{\sqrt{t^2 + \bar{W}_2^4}} \frac{dt}{t}$$

where

$$\begin{aligned} \bar{H}_4 &:= \sin \frac{H}{4} & \bar{J}_4 &:= \sin \frac{J}{4} & \bar{K}_4 &:= \sin \frac{K}{4} & \bar{W}_2^2 &:= \sin^2 \frac{W}{2} = 2\bar{H}_4\bar{J}_4\bar{K}_4 + \bar{H}_4^2 + \bar{J}_4^2 + \bar{K}_4^2 \\ t_0 &:= \frac{\bar{H}_4\bar{J}_4\bar{K}_4 \left(1 - 2\bar{H}_4\bar{J}_4\bar{K}_4 - \bar{H}_4^2 - \bar{J}_4^2 - \bar{K}_4^2\right)}{\sqrt{(\bar{H}_4 + \bar{J}_4\bar{K}_4)(\bar{J}_4 + \bar{K}_4\bar{H}_4)(\bar{K}_4 + \bar{H}_4\bar{J}_4)}} \end{aligned}$$

Given that \bar{W}_2 can be expressed in terms of H_4 , J_4 , and K_4 , the formula is effectively “pure pseudo”. In Euclidean space, the corresponding formulas for an “equihedral” tetrahedron are $W = \frac{1}{2}\sqrt{H^2 + J^2 + K^2}$ and $V = \frac{1}{3}\sqrt{HJK}$. (The simplicity of the Euclidean volume result raises the question: Does the hyperbolic volume integral have a simpler representation?)

Let us see how perfection affects this scenario.

A perfect symmetric tetrahedron necessarily has six congruent dihedral angles.¹² Consequently, its three pseudo-face areas are equal.¹³ This gives a reduced volume formula of the form

$$(12) \quad V = \int_{t_0}^{\infty} 3 \arcsin \frac{\bar{W}_2^2 - 2\bar{H}_4^2}{\sqrt{t^2 + \bar{W}_2^4}} - \arcsin \frac{\bar{W}_2^2}{\sqrt{t^2 + \bar{W}_2^4}} \frac{dt}{t}$$

where

$$\begin{aligned} \bar{W}_2^2 &= 2\bar{H}_4^3 + 3\bar{H}_4^2 \\ t_0 &:= \frac{\bar{H}_4^2 (1 + \bar{H}_4) (1 - 2\bar{H}_4)}{\sqrt{\bar{H}_4 (1 + \bar{H}_4)}} = \bar{H}_4 (1 - 2\bar{H}_4) \sqrt{\bar{H}_4 (1 + \bar{H}_4)} \end{aligned}$$

The reduced Third Law of Cosines reduces further to provide a simpler bridge between the face area and pseudo-face area.

$$\bar{W}_2^2 = 2\bar{H}_4^3 + 3\bar{H}_4^2$$

We can thus solve for H in terms of W , generating three candidates:

¹²Equality of opposite dihedral angles, coupled with the perfection condition (4), guarantees this.

¹³Without a geometric interpretation of pseudo-faces, the word “congruent” isn’t appropriate.

$$\bar{H}_4 = \frac{1}{2} \left(2 \cos \frac{W - \pi}{3} - 1 \right), \quad \frac{1}{2} \left(2 \cos \frac{W + \pi}{3} - 1 \right), \quad -\frac{1}{2} \left(1 + 2 \cos \frac{W}{3} \right)$$

The area of the hyperbolic triangle W is bounded above by π , and the area of the pseudo-face H is bounded above by 2π so that \bar{H}_4 must be non-negative. This eliminates all candidate values except the first. From this we deduce the following:

Theorem 5.2 (The Heron Formula for Volume of a Perfect Symmetric Hyperbolic Tetrahedron). *A perfect symmetric hyperbolic tetrahedron with face area W (and pseudo-face area H) has volume given by*

$$(13) \quad V = \int_{t_0}^{\infty} 3 \arcsin \frac{\bar{W}_2^2 - 2\bar{H}_4^2}{\sqrt{t^2 + \bar{W}_2^2}} - \arcsin \frac{\bar{W}_2^2}{\sqrt{t^2 + \bar{W}_2^2}} \frac{dt}{t}$$

where

$$\bar{W}_2 := \sin \frac{W}{2} \quad \bar{H}_4 := \sin \frac{H}{4} = \frac{1}{2} \left(2 \cos \frac{W - \pi}{3} - 1 \right)$$

and

$$t_0 = 2 \left(2 \cos \frac{W - \pi}{3} - 1 \right) \sin^2 \frac{W - \pi}{6} \sqrt{\sin \frac{W}{3} \sin \frac{W + \pi}{3}}$$

Again, the simplicity of the Euclidean counterpart formulas — $H^2 = \frac{4}{3}W^2$ and $V^4 = \frac{64}{2187}W^6$ — suggests that this result has a more elegant presentation.

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